



# On The Representation of Some n-Plithogenic Differential Operators by Matrices

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## Abstract

The main goal of this paper is to study the representation of the symbolic n-plithogenic differential operator for many different values of n by classical algebraic matrices and plithogenic matrices. We present many examples about the representation of symbolic n-plithogenic differential operators by matrices. As well as, we compute the symbolic 2-plithogenic, 3-plithogenic, and 4-plithogenic Wronskian, and anti-Wronskian.

**Keywords:** Differential operator, Wronskian, anti-Wronskian, symbolic n-plithogenic matrix

## Introduction

Symbolic n-plithogenic structures and sets are defined for the first time by Smarandache [4], as extensions of classical algebraic structures. Where they were used widely by many researchers to generalize famous algebraic structures. For example, we can see symbolic n-plithogenic rings, probability, spaces, and matrices [1-3, 5-8, 14-19].

The main results about symbolic n-plithogenic structures are the similarity between them and refined neutrosophic structures, see [9-13].

In this work, we concentrate on the analytical side of symbolic n-plithogenic algebraic structures, where we provide many examples about the applications of matrices in representing symbolic n-plithogenic differential operators. Also, we present the concept of symbolic n-plithogenic Wronskian, and anti-Wronskian,

with many computable examples. For the definitions of symbolic n-plithogenic rings and structures, check [1,6,8,19].

**Main Discussion**

**Definition:**

Let  $f: 2 - SP_R \rightarrow 2 - SP_R$  be a symbolic 2-plithogenic real function, we define the symbolic 2-plithogenic differential operator as:  $D_2(f) = \dot{f}$ .

**Definition.**

Let  $f: 3 - SP_R \rightarrow 3 - SP_R$  be a symbolic 3-plithogenic real function, we define the symbolic 2-plithogenic differential operator as:  $D_3(f) = \dot{f}$ .

**Definition.**

Let  $f: 4 - SP_R \rightarrow 4 - SP_R$  be a symbolic 4-plithogenic real function, we define the symbolic 2-plithogenic differential operator as:  $D_4(f) = \dot{f}$ .

**Definition.**

Let  $f: 5 - SP_R \rightarrow 5 - SP_R$  be a symbolic 5-plithogenic real function, we define the symbolic 2-plithogenic differential operator as:  $D_5(f) = \dot{f}$ .

**Example.**

Consider  $f: 2 - SP_R \rightarrow 2 - SP_R; f(X) = X^2 + (P_1 + P_2)X - P_1$ , where  $X = x_0 + x_1P_1 + x_2P_2 \in 2 - SP_R$ , then  $D_2(f) = 2X + (P_1 + P_2)$ .

Consider  $g: 3 - SP_R \rightarrow 3 - SP_R; g(X) = X^2 + P_3X + P_3 + P_2$ , where  $X = x_0 + x_1P_1 + x_2P_2 + x_3P_3 \in 3 - SP_R$ , then  $D_3(g) = 2X + P_3$ .

Consider  $h: 4 - SP_R \rightarrow 4 - SP_R; h(X) = X^3 + (P_1 + P_4)X - 1$ , where  $X = x_0 + x_1P_1 + x_2P_2 + x_3P_3 + x_4P_4 \in 4 - SP_R$ , then  $D_3(h) = 3X^2 + P_1 + P_4$ .

**Example.**

Consider  $D_2$  the symbolic 2-plithogenic differential operator on the space of symbolic 2-plithogenic quadratic polynomials  $\{aX^2 + bX + c; a, b, c, X \in 2 - SP_R\}$ , then:

$$\begin{cases} D_2(X^2) = 2X = 2x_0 + 2x_1P_1 + 2x_2P_2 = 0X^2 + 2X + 0.1 \\ D_2(X) = 1 = 0X^2 + 0.X + 1.1 \\ D_2(1) = 0 = 0X^2 + 0.X + 0.1 \end{cases}$$

Hence  $[D_2] = \begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix}$ .

**Example.**

Consider  $D_3, D_4, D_5$  be the symbolic 3-plithogenic, 4-plithogenic, 5-plithogenic differential operators on the spaces of cubic symbolic 30plithogenic, 4-plithogenic, and 5-plithogenic spaces.

$L_1 = \{aX^3 + bX^2 + bX + d; a, b, c, d, X \in 3 - SP_R\}$

$L_2 = \{aX^3 + bX^2 + bX + d; a, b, c, d, X \in 4 - SP_R\}$

$L_3 = \{aX^3 + bX^2 + bX + d; a, b, c, d, X \in 5 - SP_R\}$

Then  $D_n(X^3) = 3X^2 = 0.X^3 + 3X^2 + 0.X + 0.1$ .

$D_n(X^2) = 2X = 0.X^3 + 0.X^2 + 2.X + 0.1$ .

$D_n(X) = 1 = 0.X^3 + 0.X^2 + 0.X + 1.1$ .

$D_n(1) = 0 = 0.X^3 + 0.X^2 + 0.X + 0.1$

For all  $3 \leq n \leq 5$ , hence:

$$[D_n] = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$

**Example.**

For  $\sin X = \sin(x_0 + x_1P_1 + x_2P_2), \cos X = \cos(x_0 + x_1P_1 + x_2P_2)$ .

We have:

$$\begin{cases} D_2(\sin X) = \cos X = 0.\sin X + 1.\cos X + 0.1 \\ D_2(\cos X) = -\sin X = -1.\sin X + 0.\cos X + 0.1 \\ D_2(1) = 0 = 0.\sin X + 0.\cos X + 0.1 \end{cases}$$

Hence  $[D_2] = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ .

For  $\sin X = \sin(x_0 + x_1P_1 + x_2P_2 + x_3P_3), \cos X = \cos(x_0 + x_1P_1 + x_2P_2 + x_3P_3)$ .

We have:

$$\begin{cases} D_3(\sin X) = \cos X \\ D_3(\cos X) = -\sin X \\ D_3(1) = 0 \end{cases}$$

Hence  $[D_3] = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ .

For  $\sin X = \sin(x_0 + x_1P_1 + x_2P_2 + x_3P_3 + x_4P_4)$ ,  $\cos X = \cos(x_0 + x_1P_1 + x_2P_2 + x_3P_3 + x_4P_4)$ .

We have:

$c$

$$\text{Hence } [D_4] = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

**Example.**

For  $\{1, X, X^2, X^3, X^4\}$ ;  $X = x_0 + x_1P_1 + x_2P_2$ , we have:

$$\begin{cases} D_2(X^4) = 4X^3 \\ D_2(X^3) = 3X^2 \\ D_2(X^2) = 2X \\ D_2(X) = 1 \\ D_2(1) = 0 \end{cases}$$

$$\text{Hence } [D_2] = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

For  $X = x_0 + \sum_{i=1}^5 x_iP_i$ , we have:

$$\begin{cases} D_5(X^4) = 4X^3 \\ D_5(X^3) = 3X^2 \\ D_5(X^2) = 2X \\ D_5(X) = 1 \\ D_5(1) = 0 \end{cases}$$

$$\text{Hence } [D_5] = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

**Example.**

Consider  $A = \{1, e^X, e^{2X}\}$ , where  $X = x_0 + x_1P_1 + x_2P_2$ ,  $B = \{1, e^Y, e^{2Y}\}$ , where  $Y = y_0 + y_1P_1 + y_2P_2 + y_3P_3$ ,  $C = \{1, e^Z, e^{2Z}\}$ , where  $Z = z_0 + z_1P_1 + z_2P_2 + z_3P_3 + z_4P_4$ ,  $D = \{1, e^T, e^{2T}\}$ , where  $T = t_0 + \sum_{i=1}^5 t_iP_i$ , then:

$$\begin{cases} D_2(1) = 0 \\ D_2(e^X) = e^X \\ D_2(e^{2X}) = 2e^{2X} \end{cases}$$

$$\text{Hence } [D_3] = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}.$$

$$\begin{cases} D_3(1) = 0 \\ D_3(e^Y) = e^Y \\ D_3(e^{2Y}) = 2e^{2Y} \end{cases}$$

$$\text{Hence } [D_3] = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}.$$

$$\begin{cases} D_4(1) = 0 \\ D_4(e^Z) = e^Z \\ D_4(e^{2Z}) = 2e^{2Z} \end{cases}$$

$$\text{Hence } [D_4] = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}.$$

$$\begin{cases} D_5(1) = 0 \\ D_5(e^T) = e^T \\ D_5(e^{2T}) = 2e^{2T} \end{cases}$$

$$\text{Hence } [D_5] = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}.$$

### Another possible representation.

We have shown that symbolic n-plithogenic differential operators can be represented by classical real matrices, now we will try to explain how they can be represented by plithogenic matrices.

### Example.

Consider  $\{1, X, X^2\}$ ;  $X = x_0 + x_1P_1 + x_2P_2$ , with  $D_2$  the symbolic 2-plithogenic differential operator, then:

$$\begin{cases} D_2(1) = 0 = 0 \cdot x_0 + 0 \cdot x_1P_1 + 0 \cdot x_2P_2 \\ D_2(X) = 1 \\ D_2(X^2) = 2X \end{cases}$$

The basis  $\{1, X, X^2\}$  can be represented as follows:

$$B_1 = \{1, x_0, x_0^2\}, B_2 = \{1, (x_0 + x_1), (x_0 + x_1)^2\}, B_3 \\ = \{1, (x_0 + x_1 + x_2), (x_0 + x_1 + x_2)^2\}$$

Any quadratic polynomial  $P(X) = aX^2 + bX + c$ ;  $a, b, c, X \in 2 - SP_R$ , with:

$$\begin{cases} a = a_0 + a_1P_1 + a_2P_2 \\ b = b_0 + b_1P_1 + b_2P_2 \\ c = c_0 + c_1P_1 + c_2P_2 \\ X = x_0 + x_1P_1 + x_2P_2 \end{cases}$$

$$\begin{aligned} P(X) &= aX^2 + bX + c \\ &= (a_0x_0^2 + b_0x_0 + c_0) \\ &\quad + P_1[(a_0 + a_1)(x_0 + x_1)^2 - a_0x_0^2 + (b_0 + b_1)(x_0 + x_1) - b_0x_0 + c_1] \\ &\quad + P_2[(a_0 + a_1 + a_2)(x_0 + x_1 + x_2)^2 - (a_0 + a_1)(x_0 + x_1)^2 \\ &\quad + (b_0 + b_1 + b_2)(x_0 + x_1 + x_2) - (b_0 + b_1)(x_0 + x_1) + c_2] \\ &= q_1(x_0) + P_1[q_2(x_0 + x_1) - q_1(x_0)] \\ &\quad + P_2[q_3(x_0 + x_1 + x_2) - q_2(x_0 + x_1)] \end{aligned}$$

Hence,  $D_2(P(X)) = D_2(q_1) + P_1[D_2(q_2) - D_2(q_1)] + P_2[D_2(q_3) - D_2(q_2)]$ , hence:

$$\begin{aligned} [D_2] &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 1 & 0 \end{pmatrix} + P_1 \left[ \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 1 & 0 \end{pmatrix} \right] + P_2 \left[ \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 1 & 0 \end{pmatrix} \right] \\ &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 2 + 2P_1 + 2P_2 \\ 0 & 1 + P_1 + P_2 & 0 \end{pmatrix} \end{aligned}$$

**The symbolic plithogenic Wronskian.**

Consider the following functions independent set:

$E = \{f_1, \dots, f_n\}$ , their wronskian is defined as follows:

$$W(E) = \begin{vmatrix} f_1 & \dots & f_n \\ \dot{f}_1 & \dots & \dot{f}_n \\ \vdots & \vdots & \vdots \\ f_1^{(n-1)} & \dots & f_n^{(n-1)} \end{vmatrix}$$

We show some examples for finding the symbolic n-plithogenic Wronskian.

**Example.**

Consider  $E_1 = \{e^X, e^{2X}; X = x_0 + x_1P_1 + x_2P_2\}$ ,  $E_2 = \{1, \sin X, \cos X; X = x_0 + x_1P_1 + x_2P_2 + x_3P_3\}$ ,  $E_3 = \{1, \tan X; X = x_0 + x_1P_1 + x_2P_2 + x_3P_3 + x_4P_4\}$ ,  $E_4 = \{1, X, X^2, X^3; X = x_0 + \sum_{i=1}^5 x_iP_i\}$ , we have:

$$\begin{aligned} W(E_1) &= \begin{vmatrix} D_2^{(0)}(e^X) & D_2^{(0)}(e^{2X}) \\ D_2(e^X) & D_2(e^{2X}) \end{vmatrix} = \begin{vmatrix} e^{x_0+x_1P_1+x_2P_2} & e^{2x_0+2x_1P_1+2x_2P_2} \\ e^{x_0+x_1P_1+x_2P_2} & 2e^{2x_0+2x_1P_1+2x_2P_2} \end{vmatrix} \\ &= e^{3x_0+3x_1P_1+3x_2P_2} \end{aligned}$$

$$W(E_2) = \begin{vmatrix} 1 & \sin\left(x_0 + \sum_{i=1}^3 x_i P_i\right) & \cos\left(x_0 + \sum_{i=1}^3 x_i P_i\right) \\ 0 & \cos\left(x_0 + \sum_{i=1}^3 x_i P_i\right) & -\sin\left(x_0 + \sum_{i=1}^3 x_i P_i\right) \\ 0 & -\sin\left(x_0 + \sum_{i=1}^3 x_i P_i\right) & -\cos\left(x_0 + \sum_{i=1}^3 x_i P_i\right) \end{vmatrix} = -\cos^2\left(x_0 + \sum_{i=1}^3 x_i P_i\right)$$

$$W(E_3) = \begin{vmatrix} 1 & \tan\left(x_0 + \sum_{i=1}^4 x_i P_i\right) \\ 0 & 1 + \tan^2\left(x_0 + \sum_{i=1}^4 x_i P_i\right) \end{vmatrix} = 1 + \tan^2\left(x_0 + \sum_{i=1}^4 x_i P_i\right)$$

$$W(E_4) = \begin{vmatrix} 1 & x_0 + \sum_{i=1}^5 x_i P_i & \left(x_0 + \sum_{i=1}^5 x_i P_i\right)^2 & \left(x_0 + \sum_{i=1}^5 x_i P_i\right)^3 \\ 0 & 1 & 2\left(x_0 + \sum_{i=1}^5 x_i P_i\right) & 3\left(x_0 + \sum_{i=1}^5 x_i P_i\right) \\ 0 & 0 & 2 & 6\left(x_0 + \sum_{i=1}^5 x_i P_i\right) \\ 0 & 0 & 0 & 6 \end{vmatrix} = 12$$

**Example.**

Consider  $E_1 = \{\ln X, e^X; X = x_0 + \sum_{i=1}^5 x_i P_i\}$ ,  $E_2 = \{\ln X, \sqrt{X}; X = x_0 + \sum_{i=1}^4 x_i P_i\}$ ,  $E_3 = \{e^X, \sin X; X = x_0 + \sum_{i=1}^3 x_i P_i\}$ , then:

$$W(E_1) = \begin{vmatrix} \ln X & e^X \\ \frac{1}{X} & e^X \end{vmatrix} = e^{x_0 + \sum_{i=1}^5 x_i P_i} \left[ \ln\left(x_0 + \sum_{i=1}^5 x_i P_i\right) - \frac{1}{x_0 + \sum_{i=1}^5 x_i P_i} \right]$$

$$W(E_2) = \begin{vmatrix} \ln X & \sqrt{X} \\ \frac{1}{X} & \frac{1}{2\sqrt{X}} \end{vmatrix} = \frac{\ln X}{2\sqrt{X}} - \frac{1}{\sqrt{X}} = \frac{\ln X - 2}{2\sqrt{X}}$$

$$= \frac{1}{\sqrt{x_0 + \sum_{i=1}^4 x_i P_i}} \left[ \ln\left(x_0 + \sum_{i=1}^4 x_i P_i\right) - 2 \right]$$

$$W(E_3) = \begin{vmatrix} e^X & \sin X \\ e^X & \cos X \end{vmatrix} = e^{x_0 + \sum_{i=1}^3 x_i P_i} \left[ \cos\left(x_0 + \sum_{i=1}^3 x_i P_i\right) - \sin\left(x_0 + \sum_{i=1}^3 x_i P_i\right) \right]$$

**Symbolic n-plithogenic anti-Wronskian.**

Let  $E = \{f_1, \dots, f_n\}$  be a set of n functions, then:

$$AW(E) = \begin{vmatrix} f_1 & f_2 & \dots & f_n \\ \int f_1 & \int f_2 & \dots & \vdots \\ \int \left( \int f_1 \right) & \vdots & \dots & \vdots \\ \vdots & \vdots & \vdots & \vdots \\ \underbrace{\int f_1}_{n-1 \text{ times}} & \underbrace{\int f_2}_{n-1 \text{ times}} & \dots & \underbrace{\int f_n}_{n-1 \text{ times}} \end{vmatrix}$$

Now, we will clarify how (AW) can be computed.

**Example.**

Consider  $E_1 = \{1, X, X^2; X = x_0 + \sum_{i=1}^2 x_i P_i\}$ ,  $E_2 = \{e^X, e^{2X}; X = x_0 + \sum_{i=1}^3 x_i P_i\}$ ,  $E_3 = \{\sin X, \cos X; X = x_0 + \sum_{i=1}^4 x_i P_i\}$ , then:

$$\begin{aligned} AW(E_1) &= \begin{vmatrix} 1 & X & X^2 \\ X & \frac{1}{2}X^2 & \frac{1}{3}X^3 \\ \frac{1}{2}X^2 & \frac{1}{6}X^3 & \frac{1}{12}X^4 \end{vmatrix} \\ &= 1 \cdot \begin{vmatrix} \frac{1}{2}X^2 & \frac{1}{3}X^3 \\ \frac{1}{6}X^3 & \frac{1}{12}X^4 \end{vmatrix} - X \begin{vmatrix} X & \frac{1}{3}X^3 \\ \frac{1}{2}X^2 & \frac{1}{12}X^4 \end{vmatrix} + X^2 \begin{vmatrix} X & \frac{1}{2}X^2 \\ \frac{1}{2}X^2 & \frac{1}{6}X^3 \end{vmatrix} \\ &= \left(\frac{1}{24} - \frac{1}{18}\right)X^6 - X \left(\frac{1}{12} - \frac{1}{6}\right)X^5 + X^2 \left(\frac{1}{6} - \frac{1}{4}\right)X^4 \\ &= X^6 \left(\frac{1}{24} - \frac{1}{18} - \frac{1}{12} + \frac{1}{6} + \frac{1}{6} - \frac{1}{4}\right) = X^6 \left(\frac{1}{24} + \frac{8}{24} - \frac{6}{24} - \frac{2}{24} - \frac{1}{18}\right) \\ &= X^6 \left(\frac{1}{24} - \frac{1}{18}\right) = -\frac{1}{72} \left(x_0 + \sum_{i=1}^3 x_i P_i\right) \end{aligned}$$

$$AW(E_2) = \begin{vmatrix} e^X & e^{2X} \\ e^X & \frac{1}{2}e^{2X} \end{vmatrix} = \frac{1}{2}e^X e^{2X} - e^X e^{2X} = -\frac{1}{2}e^{3X} = -\frac{1}{2}e^{(x_0 + \sum_{i=1}^3 x_i P_i)}$$



$$\begin{aligned}
AW(E_3) &= \begin{vmatrix} \sin X & \cos X & 1 \\ -\cos X & -\sin X & X \\ -\sin X & -\cos X & \frac{1}{2}X^2 \end{vmatrix} \\
&= \sin X \cdot \begin{vmatrix} \sin X & X \\ -\cos X & \frac{1}{2}X^2 \end{vmatrix} - \cos X \begin{vmatrix} -\cos X & X \\ -\sin X & \frac{1}{2}X^2 \end{vmatrix} + 1 \cdot \begin{vmatrix} -\cos X & \sin X \\ -\sin X & -\cos X \end{vmatrix} \\
&= \sin X \left( \frac{1}{2}X^2 \sin X + X \cos X \right) - \cos X \left( -\frac{1}{2}X^2 \cos X + X \sin X \right) \\
&\quad + (\cos^2 X + \sin^2 X) \\
&= \frac{1}{2}X^2 \sin^2 X + X \cos X \sin X + \frac{1}{2}X^2 \cos^2 X - X \cos X \sin X + 1 \\
&= \frac{1}{2}X^2(1) + 1 = \frac{1}{2} \left( x_0 + \sum_{i=1}^4 x_i P_i \right) + 1
\end{aligned}$$

## Conclusion

In this paper, we have studied the representation of the symbolic n-plithogenic differential operator for many different values of n by classical algebraic matrices and plithogenic matrices. We presented many examples about the representation of symbolic n-plithogenic differential operators by matrices. As well as, we computed the symbolic 2-plithogenic, 3-plithogenic, and 4-plithogenic Wronskian, and anti-Wronskian.

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