



Harmonic Mean Operator Based MADM-Strategy under SVPN-Set Environment Bimal Shil¹, Suman Das², Rakhal Das^{3,*}, and Binod Chandra Tripathy⁴ ¹Department of Statistics, Tripura University, Agartala, 799022, Tripura, India. Email: bimalshil738@gmail.com ²Department of Mathematics, Tripura University, Agartala, 799022, Tripura, India. Email: sumandas18842@gmail.com, dr.suman1995@yahoo.com, dr.sumandas1995@gmail.com ³Department of Mathematics, The ICFAI University, Agartala, 799210, Tripura, India. Email: rakhaldas95@gmail.com, rakhaldas@iutripura.edu.in ⁴Department of Mathematics, Tripura University, Agartala, 799022, Tripura, India. Email: tripathybc@gmail.com, tripathybc@yahoo.com *Correspondence: rakhaldas95@gmail.com

Abstract: By using single-valued pentapartitioned neutrosophic set (briefly SVPN-set), one can express uncertainty events having incomplete, indeterminate, and erroneous information in practical applications. This study's primary goal is to present a multi-attribute decision-making (briefly MADM) algorithm that operates in the SVPN-set environment using the notion of single-valued pentapartitioned neutrosophic harmonic mean (briefly SVPNHM) operator and single-valued pentapartitioned neutrosophic weighted harmonic mean (briefly SVPNWHM) operator. Further, we provide a numerical illustration here like, "Location Selection for Installation of Outdoor Air Purifier" to validate the effectiveness and rationality of the proposed MADM algorithm.

Keywords: SVPN-set; Indeterminacy; MADM; SVPNHM-operator; SVPNWHM-operator.

1. Introduction:

During 1998, Smarandache [28] presented the idea of neutrosophic set (briefly N-set) and neutrosophic number (briefly N-number), which address uncertain and deficient data in another manner. Two components make up an N-number: a determinate part and an indeterminate part. In this manner, the N-numbers are more effective to manage uncertain and deficient data in certifiable issues. Afterwards, Wang et al. [29] grounded and studied single-valued N-set (briefly SVN-set). MADM and multi-attribute group decision-making (briefly MAGDM) are two critical parts of choice speculations which have been ordinarily applied in numerous logical fields. Till now, many researchers around the globe used SVN-set in their theoretical research [10, 11, 14, 17] and also

proposed several MADM and MAGDM techniques [3, 9, 18, 20-23, 26-28] under the SVN-set environment. In the year 2009, Xu [30] presented the notion of harmonic mean operator under the fuzzy environment. Afterwards, Aydin et al. [2] developed a harmonic aggregation operator under trapezoidal Pythagorean fuzzy number environment. A MAGDM approach in fuzzy environment was suggested by Park et al. [25] using generalized fuzzy bonferroni harmonic mean operator. Later, in an intuitionistic fuzzy environment, Zhou et al. [32] presented a MADM method using the normalized weighted bonferroni harmonic mean operator. Thereafter, Mondal et al. [22] proposed a MAGDM strategy based on normalized neutrosophic harmonic mean operator under the SVN-set environment. The principles of SVPN-set and single-valued pentapartitioned neutrosophic number (briefly SVPN-number) were initially introduced in 2020 by Mallick and Pramanik [19]. In the context of the SVPN-set environment, Das et al. [6] came up with a tangent similarity based MADM approach. Afterwards, Das et al. [5] established a MADM algorithm using grey relational analysis method in the context of SVPN-set environment.

The main goal of this research is to demonstrate a novel MADM methodology using the on the SVPNWHM operator. Furthermore, we validate our MADM methodology by providing a real life example, namely "Location Selection for Installation of Outdoor Air Purifier".

The rest of this paper is organized in the following manner:

A few preliminary results on SVPN-set as well as score and accuracy function of SVPN-numbers are shown in section-2. In section-3, two aggregation operators namely, SVPNHM operator and SVPNWHM operator have been introduced. Besides, a unique MADM methodology based on the SVPNWHM operator is presented in section-4. The suggested MADM methodology is demonstrated using a numerical example in section-5, and the outcomes demonstrate their viability and efficacy. In section-6, we provide some closing thoughts and outline some potential areas for further investigation.

2. Preliminaries and Definitions:

The idea of SVPN-set theory was first grounded in 2020 by Mallick and Pramanik [19]. They achieved this by dividing the indeterminacy-membership into three distinct categories: contraction, ignorance and unknown-memberships. Below are the concepts of SVPN-set and SVPN-number. **Definition 2.1.**[19] Consider Ü be a non-null set. Then *H*, a SVPN-set over Ü is defined by

 $D=\{(\hat{e}, \check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{G}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{N}_{D}(\hat{e})) : \hat{e} \in \check{U}\},\$

where $\hat{T}_{\mathcal{D}}(\hat{e})$, $\hat{C}_{\mathcal{D}}(\hat{e})$, $\check{G}_{\mathcal{D}}(\hat{e})$, $\check{U}_{\mathcal{D}}(\hat{e})$ and $\check{N}_{\mathcal{D}}(\hat{e})$ are the truth, contradiction, ignorance, unknown and falsity membership function lies in the interval [0,1] such that

 $0 \leq \check{T}_{D}(\hat{e}) + \check{C}_{D}(\hat{e}) + \check{G}_{D}(\hat{e}) + \check{U}_{D}(\hat{e}) + \check{N}_{D}(\hat{e}) \leq 5, \forall \hat{e} \in \ddot{U}.$

For each $\vec{e} \in \vec{U}$, $[\check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{G}_{D}(\hat{e}), \check{V}_{D}(\hat{e}), \check{N}_{D}(\hat{e})]$ is referred to as a SVPN-number.

Definition 2.2.[19] Assume that Ü be a non-empty set. Suppose that $D=\{(\hat{e}, \check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{G}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{N}_{D}(\hat{e})\}$ $\check{N}_{D}(\hat{e})\}: \hat{e} \in U\}$ and $Q=\{(\hat{e}, \check{T}_{Q}(\hat{e}), \check{C}_{Q}(\hat{e}), \check{G}_{Q}(\hat{e}), \check{V}_{Q}(\hat{e}), \check{N}_{Q}(\hat{e})\}: \hat{e} \in U\}$ be two SVPN-sets defined over Ü. Then, $D\subseteq Q$ if and only if $\check{T}_{D}(\hat{e}) \leq \check{T}_{Q}(\hat{e}), \check{C}_{D}(\hat{e}) \leq \check{C}_{Q}(\hat{e}), \check{G}_{D}(\hat{e}) \geq \check{G}_{Q}(\hat{e}), \check{U}_{D}(\hat{e}) \geq \check{U}_{Q}(\hat{e}), \check{N}_{D}(\hat{e}) \geq \check{N}_{Q}(\hat{e}), \forall \hat{e} \in U.$

Definition 2.3.[19] Assume that Ü be a non-empty set. Suppose that $D=\{(\hat{e}, \check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{G}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{N}_{D}(\hat{e})): \hat{e} \in \ddot{U}\}$ and $Q=\{(\hat{e}, \check{T}_{Q}(\hat{e}), \check{C}_{Q}(\hat{e}), \check{G}_{Q}(\hat{e}), \check{U}_{Q}(\hat{e}), \check{N}_{Q}(\hat{e})): \hat{e} \in \ddot{U}\}$ be two SVPN-sets defined over Ü. Then, their intersection is defined by $D \cap Q = \{(\hat{e}, \min\{\check{T}_{D}(\hat{e}), \check{T}_{Q}(\hat{e})\}, \min\{\check{C}_{D}(\hat{e}), \check{C}_{Q}(\hat{e})\}, \max\{\check{G}_{D}(\hat{e}), \check{G}_{Q}(\hat{e})\}, \max\{\check{N}_{D}(\hat{e}), \check{N}_{Q}(\hat{e})\}): \hat{e} \in \ddot{U}\}.$

Definition 2.4.[19] Assume that Ü be a non-empty set. Suppose that $D=\{(\hat{e}, \check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{G}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{N}_{D}(\hat{e})): \hat{e} \in U\}$ and $Q=\{(\hat{e}, \check{T}_{Q}(\hat{e}), \check{C}_{Q}(\hat{e}), \check{G}_{Q}(\hat{e}), \check{U}_{Q}(\hat{e}), \check{N}_{Q}(\hat{e})): \hat{e} \in U\}$ be two SVPN-sets defined over Ü. Then, their union is defined by $D \cup Q = \{(\hat{e}, \max\{\check{T}_{D}(\hat{e}), \check{T}_{Q}(\hat{e})\}, \max\{\check{C}_{D}(\hat{e}), \check{C}_{Q}(\hat{e})\}, \min\{\check{G}_{D}(\hat{e}), \check{G}_{Q}(\hat{e})\}, \min\{\check{U}_{D}(\hat{e}), \check{U}_{Q}(\hat{e})\}, \min\{\check{N}_{D}(\hat{e}), \check{N}_{Q}(\hat{e})\}): \hat{e} \in U\}.$

Definition 2.5.[19] Assume that \ddot{U} be a non-empty set. Suppose that $D=\{(\vec{e}, \check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{G}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{N}_{D}(\hat{e})\}$ be a SVPN-set defined over \ddot{U} . Then, the complement of D is $D^{c} = \{(\vec{e}, \check{N}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{U}$

Definition 2.6.[28] Assume that $\hat{e}=[\check{T}_{D}(\hat{e}), \check{C}_{D}(\hat{e}), \check{U}_{D}(\hat{e}), \check{N}_{D}(\hat{e})]$ and $\check{\eta}=[\check{T}_{D}(\check{\eta}), \check{C}_{D}(\check{\eta}), \check{G}_{D}(\check{\eta}), \check{U}_{D}(\check{\eta}), \check{V}_{D}(\check{\eta})]$ be two different SVPN-numbers over \ddot{U} . Then,

(*i*) $\vec{e} \subseteq \tilde{\eta}$ if and only if $\check{T}_{\mathcal{D}}(\hat{e}) \leq \check{T}_{\mathcal{D}}(\tilde{\eta}), \check{C}_{\mathcal{D}}(\hat{e}) \leq \check{C}_{\mathcal{D}}(\tilde{\eta}), \check{G}_{\mathcal{D}}(\hat{e}) \geq \check{G}_{\mathcal{D}}(\tilde{\eta}), \check{U}_{\mathcal{D}}(\hat{e}) \geq \check{U}_{\mathcal{D}}(\tilde{\eta}), \check{N}_{\mathcal{D}}(\hat{e}) \geq \check{N}_{\mathcal{D}}(\tilde{\eta});$

 $(ii) \ \hat{\mathbf{e}} = \tilde{\boldsymbol{\eta}} \ \text{if and only if } \check{\mathbf{T}}_{\mathcal{D}}(\hat{\mathbf{e}}) = \check{\mathbf{T}}_{\mathcal{D}}(\tilde{\boldsymbol{\eta}}), \ \check{\mathbf{C}}_{\mathcal{D}}(\hat{\mathbf{e}}) = \check{\mathbf{C}}_{\mathcal{D}}(\hat{\mathbf{e}}), \ \check{\mathbf{G}}_{\mathcal{D}}(\hat{\mathbf{e}}) = \check{\mathbf{G}}_{\mathcal{D}}(\tilde{\boldsymbol{\eta}}), \ \check{\mathbf{U}}_{\mathcal{D}}(\hat{\mathbf{e}}) = \check{\mathbf{U}}_{\mathcal{D}}(\tilde{\boldsymbol{\eta}}), \ \check{\mathbf{N}}_{\mathcal{D}}(\hat{\mathbf{e}}) = \check{\mathbf{N}}_{\mathcal{D}}(\tilde{\boldsymbol{\eta}});$

(*iii*) μ . $\vec{e} = [1-(1-\check{T}_{D}(\hat{e}))^{\mu}, 1-(1-\check{C}_{D}(\hat{e}))^{\mu}, (\check{D}_{D}(\hat{e}))^{\mu}, (\check{N}_{D}(\hat{e}))^{\mu}], \text{ where } \mu > 0;$

 $(iv) \hat{e}^{\mu} = [(\check{T}_{D}(\hat{e}))^{\mu}, (\check{C}_{D}(\hat{e}))^{\mu}, 1-(1-\check{G}_{D}(\hat{e}))^{\mu}, 1-(1-\check{U}_{D}(\hat{e}))^{\mu}, 1-(1-\check{N}_{D}(\hat{e}))^{\mu}], \text{ where } \mu > 0;$

 $(v) \ \hat{e} + \hat{\eta} = [\check{T}_{\mathcal{D}}(\hat{e}) + \check{T}_{\mathcal{D}}(\hat{\eta}) - \check{T}_{\mathcal{D}}(\hat{e}) \cdot T_{\mathcal{D}}(\hat{\eta}), \ \check{C}_{\mathcal{D}}(\hat{e}) + C_{\mathcal{D}}(\hat{\eta}) - \check{C}_{\mathcal{D}}(\hat{e}) \cdot \check{C}_{\mathcal{D}}(\hat{\eta}), \ \check{G}_{\mathcal{D}}(\hat{e}) \cdot \check{G}_{\mathcal{D}}(\hat{\eta}), \ \check{U}_{\mathcal{D}}(\hat{e}) \cdot \check{U}_{\mathcal{D}}(\hat{\eta}), \ \check{N}_{\mathcal{D}}(\hat{e}) \cdot \check{N}_{\mathcal{D}}(\hat{\eta})];$

 $(vi) \stackrel{e}{e}. \stackrel{e}{\eta} = [\stackrel{T}{D}(\stackrel{e}{e}).\stackrel{T}{D}(\stackrel{e}{\eta}), \stackrel{C}{O}=\stackrel{e}{e}).C_{\mathcal{D}}(\stackrel{e}{\eta}), \stackrel{G}{O}=\stackrel{e}{O}=\stackrel{G}$

Definition 2.7. [28] Suppose that $\hat{e}=[\check{T}_{D}(\hat{e}),\check{C}_{D}(\hat{e}),\check{U}_{D}(\hat{e}),\check{N}_{D}(\hat{e})]$ be a SVPN-number over \ddot{U} . Then, (*i*) score function is defined as follows:

$$S(\hat{e}) = \frac{[\check{T}_{\mathbb{D}}(\hat{e}) + \check{C}_{\mathbb{D}}(\hat{e}) + 1 - \check{G}_{\mathbb{D}}(\hat{e}) + 1 - \check{U}_{\mathbb{D}}(\hat{e}) + 1 - \check{N}_{\mathbb{D}}(\hat{e})]}{5}$$
(1)

(*ii*) accuracy function is defined as follows:

$$A(\hat{\mathbf{e}}) = \frac{[\check{\mathbf{T}}_{\mathbb{D}}(\hat{\mathbf{e}}) + \check{\mathbf{C}}_{\mathbb{D}}(\hat{\mathbf{e}}) - \check{\mathbf{N}}_{\mathbb{D}}(\hat{\mathbf{e}})]}{3}$$
(2)

Definition 2.8.[28] Let $\hat{e}=[\check{T}_{\mathcal{D}}(\hat{e}), \check{C}_{\mathcal{D}}(\hat{e}), \check{U}_{\mathcal{D}}(\hat{e}), \check{N}_{\mathcal{D}}(\hat{e})]$ and $\check{\eta}=[\check{T}_{\mathcal{D}}(\check{\eta}), \check{C}_{\mathcal{D}}(\check{\eta}), \check{U}_{\mathcal{D}}(\check{\eta}), \check{N}_{\mathcal{D}}(\check{\eta})]$ be two SVPN-numbers defined over \ddot{U} . Then,

- (i) $S(\hat{e}) > S(\tilde{\eta}) \Longrightarrow \hat{e} > \tilde{\eta};$
- (*ii*) $S(\hat{e}) = S(\tilde{\eta}), A(\hat{e}) > A(\tilde{\eta}) \Rightarrow \hat{e} > \tilde{\eta};$
- (*iii*) $S(\hat{e}) = S(\tilde{\eta}), A(\hat{e}) = A(\tilde{\eta}), T_{\kappa}(\hat{e}) > T_{\kappa}(\tilde{\eta}) \Rightarrow \hat{e} > \tilde{\eta}.$

Proposition 2.1.[28] The accuracy and score functions of a SVPN-number are bounded.

Proposition 2.2.[28] The accuracy and score functions of a SVPN-number are monotone.

3. Single-Valued Pentapartitioned Neutrosophic Harmonic Mean Operator:

Here, we introduce the notions of SVPNHM operator and SVPNWHM operator under the SVPN-set environment.

Definition 3.1. Suppose that $\vec{e}_t = [\check{\mathbf{T}}_{\kappa}(\vec{e}_t), \check{\mathbf{C}}_{\kappa}(\vec{e}_t), \check{\mathbf{U}}_{\kappa}(\vec{e}_t), \check{\mathbf{N}}_{\kappa}(\vec{e}_t)]$ (*t*=1, 2, 3, ..., *y*) be the family of SVPN-numbers over $\ddot{\mathbf{U}}$. Then, the SVPNHM operator is defined as follows:

SVPNHM
$$(\vec{e}_1, \vec{e}_2, ..., \vec{e}_y) = \frac{y}{\sum_{t=1}^{y} \frac{1}{\tilde{e}_t}}$$
 (3)

where $\frac{1}{v_t} = [1/(\check{T}_R(\hat{e})+1), 1/(\check{C}_R(\hat{e})+1), 1/(\check{G}_R(\hat{e})+1), 1/(\check{U}_R(\hat{e})+1), 1/(\check{N}_R(\hat{e})+1)]$ (4)

Example 3.1. Let u = (0.6, 0.2, 0.6, 0.2, 0.7) and v = (0.7, 0.2, 0.1, 0.4, 0.5) be two SVPN-numbers over \ddot{U} . Then, SVPNHM $(u, v) = 2 \cdot \frac{1}{(\frac{1}{u} + \frac{1}{v})} = (0.86, 0.79, 0.27, 0.34, 0.36)$, which is also a SVPN-number.

Definition 3.2. Suppose that $\vec{e}_t = [\check{\mathbf{T}}_{\kappa}(\vec{e}_t), \check{\mathbf{C}}_{\kappa}(\vec{e}_t), \check{\mathbf{U}}_{\kappa}(\vec{e}_t), \check{\mathbf{N}}_{\kappa}(\vec{e}_t)]$ (*t*=1, 2, 3, ..., *y*) be the family of SVPN-numbers over $\ddot{\mathbf{U}}$. Then, the SVPNWHM operator is defined as follows:

SVPNWHM (
$$\hat{e_1}, \hat{e_2}, \dots, \hat{e_y}$$
) = $\frac{y}{\sum_{t=1}^{y} \frac{\delta_t}{\delta_t}}$, (5)

where δ_t is the corresponding weight of \hat{e}_t (*t*=1,2,..., *y*), such that $\delta_t \in [0,1]$ and $\sum_{t=1}^{y} \delta_t = 1$.

Example 3.2. Let u=(0.8, 0.2, 0.7, 0.4, 0.3) and v=(0.6, 0.5, 0.4, 0.3, 0.2) be two SVPN-numbers over \ddot{U} . Let $\delta_1=0.5$ and $\delta_2=0.4$ be the corresponding weighted value of u and v.

Then, SVPNWHM $(u, v) = 2 \cdot \frac{1}{\left(\frac{\delta_1}{u} + \frac{\delta_2}{v}\right)} = 2 \cdot \frac{1}{\left(\delta_1 \cdot \left(\frac{1}{u}\right) + \delta_2 \cdot \left(\frac{1}{v}\right)\right)} = (0.32, 0.34, 0.81, 0.85, 0.80)$, which is also

a SVPN-number.

4. SVPNWHM Operator Based MADM Strategy under the SVPN-set Environment:

This section developed a MADM technique using SVPNWHM operator under the SVPN-set environment.

In a MADM problem, suppose that, Θ be the set of *n* alternatives namely Θ_1 , Θ_2 ,..., Θ_n , and Å be the set of *m* attributes namely Å₁, Å₂,..., Å_m. Assume that, the decision maker gives his/her evaluation information for each alternative Θ_i (*i*=1, 2, ..., *n*) corresponding to the attributes Å_j (*j*=1, 2, ..., *m*) by using the SVPN-sets as follows:

$$\Theta_i = \{(\mathring{A}_i, \check{T}_{\Theta_i}(\mathring{A}_j), \check{C}_{\Theta_i}(\mathring{A}_j), \check{G}_{\Theta_i}(\mathring{A}_j), \check{U}_{\Theta_i}(\mathring{A}_j), \check{N}_{\Theta_i}(\mathring{A}_j)\}: \mathring{A}_j \in \mathring{A}\},\$$

where $0 \leq \check{T}_{\Theta_i}(\mathring{A}_j) + C_{\Theta_i}(\mathring{A}_j) + \check{G}_{\Theta_i}(\mathring{A}_j) + \check{U}_{\Theta_i}(\mathring{A}_j) + \check{N}_{\Theta_i}(\mathring{A}_j) \leq 5$, for each *i*=1,2,..., *n*, and *j*=1,2,..., *m*. For convenience,

 $\Theta_{ij}=(\check{T}_{ij},\check{C}_{ij},\check{G}_{ij},\check{U}_{ij},\check{N}_{ij}) \text{ denotes the SVPN-number } (\check{T}_{\Theta_i}(\check{A}_j),\check{C}_{\Theta_i}(\check{A}_j),\check{U}_{\Theta_i}(\check{A}_j),\check{U}_{\Theta_i}(\check{A}_j),\check{N}_{\Theta_i}(\check{A}_j)) \text{ in the SVPN-set } \Theta_i(i=1,2,...,n).$

Then, the single-valued pentapartitioned neutrosophic decision matrix is denoted by $D=(A_{ij})_{n \times m}$.

Our suggested MADM methodology consists of the subsequent steps:

Step-1: Start

Step-2: Formation of the Decision Matrix

By utilizing the assessment data of each alternative against each attribute, the decision maker constructed the decision matrix in this step.

Step-3: Calculate the Weights of Each Attribute

In this step, the decision maker can calculate the weight of each attribute by using the compromise function, which is described as follows:

Compromise Function:

For each attribute \hat{w}_i (*j*=1, 2, ...,*m*), the compromise function is defined by:

$$\Omega_{j} = \sum_{i=1}^{n} (3 + \check{\mathbf{T}}_{\Theta_{i}}(\mathring{A}_{j}) + \check{\mathbf{C}}_{\Theta_{i}}(\mathring{A}_{j}) - \check{\mathbf{G}}_{\Theta_{i}}(\mathring{A}_{j}) - \check{\mathbf{U}}_{\Theta_{i}}(\mathring{A}_{j}) - \check{\mathbf{N}}_{\Theta_{i}}(\mathring{A}_{j}))/5$$

$$\tag{6}$$

The jth attribute's weights are then determined as follows:

$$\hat{\mathbf{W}}_{j} = \frac{\Omega_{j}}{\sum_{j=1}^{m} \Omega_{j}}$$
(7)

Here, $\sum_{i=1}^{m} \hat{w}_i = 1$.

Step-4. Calculation of Aggregate Value using the SVPNWHM Operator

In this stage, the decision maker can use eq. (4) and eq. (5) to calculate the aggregate value of all the attributes with respect to the corresponding alternative.

Step-5. Determine the Score Value of Each Alternative with respect to the Aggregate Value

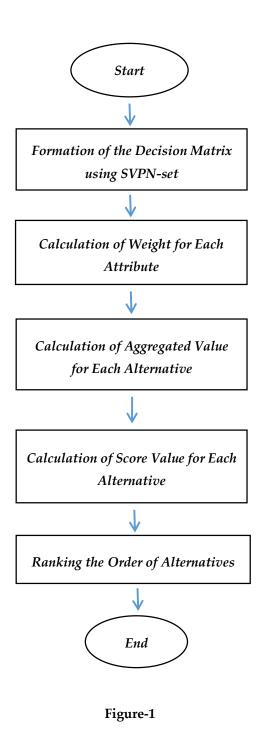
Using equations (1) and (2), the decision maker calculates each alternative's score and accuracy value in relation to the aggregate values of all alternatives in this stage.

Step-6. Ranking of the Alternatives

In this stage, the decision-maker uses Definition 2.8 to assign a rank to each choice.

Step-7. End

The flow chart of our proposed MADM strategy was shown by the following flow chart:



5. Validation of the Proposed MADM-Strategy:

Example 5.1. "Location Selection for the Installation of Outdoor Air Purifier".

Suppose that, the state government of any state (of India) wants to install an Air Purifier in a particular area to supply the fresh air in the environment to neutralize the air concentration. Let the government initiates to select the appropriate place for the installation of Air Purifier. After the initial screening, the decision makers select four alternatives (areas) Ă₁, Ă₂ and Ă₃, for further evaluation.

The appropriate and scientific process that makes the fresh air from pollute air is done by air purifier. The process must improve the quality of air in the environment. Air pollution means where we meet the undesired concentration of impurities in air. After the filtering Air by purifier it remove dust, airborne bacteria, airborne particles, neutralize smoke, and many other particles.

The following are the stages of the air purifier treatment plants:

- (*a*) Absorbed pollute Air,
- (b) Removed visible particle by using pad filter and pleated filter,
- (c) Carbon filtering it removes odors and capture gases and organic compound from smoke,
- (d) Capture microscope particles,
- (e) Supply fresh air,
- (*f*) Changing filter.

The organic and inorganic components are filtered naturally. To increase the air quality at indoor normally used air purifier, there are few natural way have noticed some of them increase Vegetation, Salt lamp, Active charcoal, House plant, Essential oil like oregano, cinnamon, rosemary. Bacteria and other harmful micro-pollutants are removed by the using ... plates. Sometimes, it is very difficult to choose a geographical area for the installation of air purifier treatment plant because of its hierarchical nature. Till now, many researchers around the globe presented their models for the selection of land for the installation of air purifier treatment plant. Based on a review of the accumulated scientific evidence some guidelines were well documented in WHO manual (WHO 2005) on four most common air pollutants- particulate matter , ozone , nitrogen dioxide and sulfur dioxide for maintaining the quality of natural air . So, the location of installation of air purifier treatment plant has also decide the type of air treatment process, steps of treatment procedures to be implemented in the pollute air treatment plant for supply of fresh air in desired level of purity. That is why the selection of location for installation or relocation of air purifier treatment plant can be treated as a MADM problem. The selection of attribute is a high factor for identifying the location for the installation of the air purifier treatment plant. For the selection of location for the installation of

air purifier treatment plant, the decision maker need to choose some attributes so that they can easily select the suitable location.

In [4], Choudhury et al. have selected four attributes namely (*i*) Technological Constraints, (*ii*) Environmental Constraints, (*iii*) Economical Constraints, (*iv*) Political Constraints, for the selection of geographical land for the installation of surface water treatment plant.

Here, we have also selected the above mentioned four attributes to select the suitable location for the installation of Air Purifier.

1. Technological Constrains (Θ₁):

Among many parameter technological constraints is one of the most important factor for the air purifier treatment like machinery selection, Engineering process, use of electrify, air quality index level (briefly AQI), different components level in air etc. Technology can help to maintain the all factors including the animal health and environment. This is why we considering technical constrain is the first criterion in this study.

2. Environmental Constrains (Θ₂):

Environmental constrains is another essential parameter for air purifier treatment plant. In case of place selection in highly pollutant and population area is a difficult task. Outside of city are not suitable since the consumption air purifier needed to install in extremely pollute places. But some time hospital, stadium, school area has to decide for installing air purifier for minimizes the other issues. The work of conventional smoke tower plants clean polluted air and minimizes air pollution.

3. Economical Constrains (Θ₃):

For the air treatment plant economical constrains is the one of the most important factor to execute the installation plane. The cost of distribution of air from the treatment to the environment and other expenditure like, machinery, labor, plates and other technology used to minimize. The use of the technological and geographical selection can help the economical constrains.

4. Political Constrains (Θ₄):

The political constrains is another basic factor for the proper installation of air purifier. The balancing of clean air management economic rationale of demand management is the work of political constrains.

By using the decision makers' evaluation information about the alternatives against each attributes we get the following decision matrix:

		Å1	Å2	Åз	Å4
e)1	(0.8,0.6,0.2,0.3,0.7)	(0.6, 0.4, 0.1, 0.5, 0.6)	(0.5,0.5,0.7,0.4,0.3)	(0.8, 0.5, 0.4, 0.2, 0.4)
e)2	(0.8, 0.6, 0.4, 0.2, 0.5)	(0.7, 0.2, 0.4, 0.6, 0.7)	(0.9, 0.3, 0.4, 0.3, 0.8)	(0.7, 0.2, 0.3, 0.6, 0.4)
e)3	(0.9, 0.5, 0.7, 0.2, 0.4)	(0.6, 0.2, 0.4, 0.7, 0.4)	(0.5, 0.4, 0.4, 0.3, 0.7)	(0.8, 0.2, 0.4, 0.6, 0.5)

Table-1

By using eq. (6) and eq. (7), we get the weight vector $\hat{w} = (\hat{w}_1, \hat{w}_2, \hat{w}_3, \hat{w}_4) = (0.2900302, 0.2205438, 0.2356495, 0.2537764)$ for the previously mentioned four attributes corresponding to the four alternatives.

Now, the decision maker can find the aggregate value of all the attributes with respect to the corresponding alternative by using eq. (4) and eq. (5). The aggregate value is given in the following table.

	Aggregate Value
SVPNWHM (Θ1: Ấ1, Ấ2, Ấ3, Ấ4)	(0.99771196, 0.70732183, 0.02562288, 0.15405526, 0.19856120)
SVPNWHM (Θ2: Ấ1, Ấ2, Ấ3, Ấ4)	(0.99820335, 0.75082793, 0.02466152, 0.15405526, 0.39608476)
SVPNWHM (Θ_3 : Ấ1, Ấ2, Ấ3, Ấ4)	(0.99686998, 0.68982898, 0.05410631, 0.17649619, 0.19856120)

Table-2

Now, we have, $S(\Theta_1)=0.8653589$, $S(\Theta_2)=0.8348459$, $S(\Theta_3)=0.8515071$, by using the eq. (1). This implies, $S(\Theta_2) < S(\Theta_3) < S(\Theta_1)$. Hence, Θ_1 is the most suitable location for the installation of the outdoor Air purifier.

6. Conclusions:

In this study, we have grounded the notion of SVPNHM operator, SVPNWHM operator, and provide some appropriate examples on them. Then, we have proposed a SVPNWHM operator based MADM technique under the SVPN-set environment. Finally, we have given a real world numerical example namely "Location Selection for the Installation of Outdoor Air Purifier" demonstrate the practical significance of our recommended MADM methodology.

The recommended MADM methodology can also be utilized for dealing with the other decision-making problems such as brick selection [20], surface water treatment plant location selection [4], logistic center location selection [26, 27], tender selection [9], etc.

Furthermore, the proposed MADM technique is expected to open up new avenues for investigation in the SVPN-Set setting.

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